

Quick start guide

Finger gripper mGrip Parallel

Note

The Quick Start Guide were originally written in German. Store in a safe place for future reference. Subject to technical changes without notice. No responsibility is taken for printing or other types of errors.

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J. Schmalz GmbH · Johannes-Schmalz-Str. 1 · 72293 Glatten, Germany · T: +49 7443 2403-0
schmalz@schmalz.de

1 Important Information

1.1 The technical documentation is part of the product

1. For problem-free and safe operation, follow the instructions in the documents.
 2. Keep the technical documentation in close proximity to the product. The documentation must be accessible to personnel at all times.
 3. Pass on the technical documentation to subsequent users.
- ⇒ Failure to follow the instructions in these Quick Start Guide may result in injuries!
- ⇒ Schmalz is not liable for damage or malfunctions that result from failure to heed these instructions.

If you still have questions after reading the technical documentation, contact Schmalz Service at:

www.schmalz.com/services

1.2 Symbols



This symbol indicates useful and important information.

- ✓ This symbol represents a prerequisite that must be met before an action is performed.
- ▶ This symbol represents an action to be performed.
- ⇒ This symbol represents the result of an action.

Actions that consist of more than one step are numbered:

1. First action to be performed.
2. Second action to be performed.

2 Fundamental Safety Instructions

2.1 Intended Use

The finger gripper mgrip Parallel gripper is designed and manufactured in a hygienic design for industrial transport tasks. For Parallel configurations with 2, 4, and 6 fingers.

It is intended to be used in combination with a robot or a handling system for gripping and holding sensitive products of the maximum specified size, including products in the food industry. The size depends on the dimensions of the products and the type of gripping.

The finger gripper is an incomplete machine as defined by the Machinery Directive 2006/42/EC. It must only be operated in combination with a robot or handling system.

The product is intended for industrial use.

Intended use includes observing the technical data and the installation and operating instructions in this manual.

2.2 Non-Intended Use

Schmalz accepts no liability for damages caused by the use of the product for purposes other than those described under "Intended Use." The use of the product for loads that are not specified in the order confirmation or have different physical properties than those specified in the order confirmation shall be considered non-intended use.

2.3 Personnel Qualifications


Unqualified personnel cannot recognize dangers and are therefore exposed to higher risks!

1. Task only qualified personnel to perform the tasks described in these Quick Start Guide.
2. The product must be operated only by persons who have undergone appropriate training.

These Quick Start Guide are intended for fitters who are trained in handling the product and who can operate and install it.

2.4 Warnings in This Document

Warnings warn against hazards that may occur when handling the product. The signal word indicates the level of danger.

Signal word	Meaning
 CAUTION	Indicates a low-risk hazard that could result in minor or moderate injury if not avoided.
NOTE	Indicates a danger that leads to property damage.

2.5 Residual Risks



CAUTION

Noise pollution caused by exhaust air or leakage during operation

Hearing damage!

- ▶ In the event of leakage, check connections and lines and remedy leakages.
- ▶ Wear ear protection.



CAUTION

Risk of a gripping finger bursting if the air pressure is too high when the gripping fingers are activated.

Risk of injury

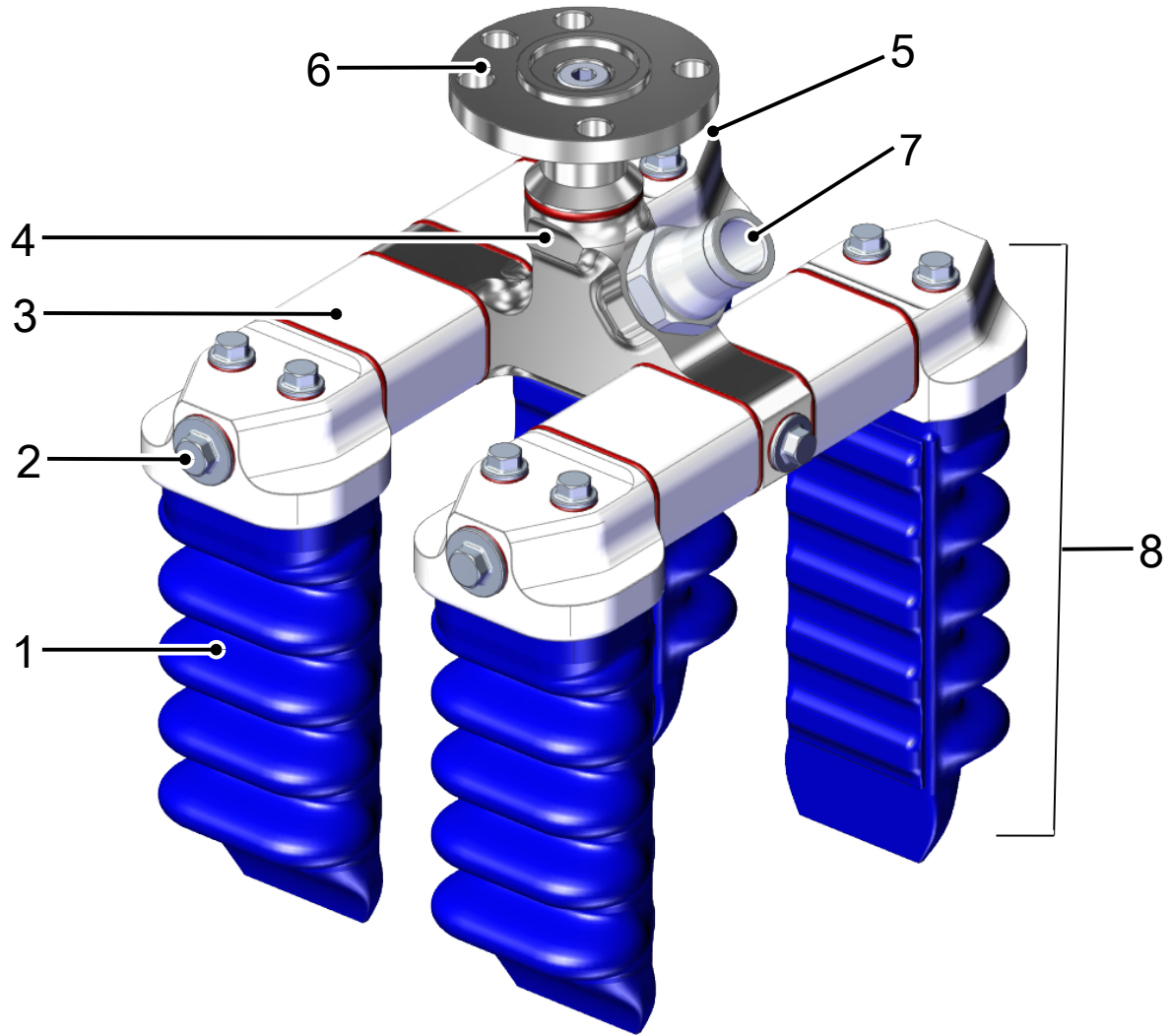
- ▶ Ensure that the gripper is operated only with the mGrip SRCUs control unit.
- ▶ Wear ear plugs and protective glasses.

2.6 Modifications to the Product

Schmalz assumes no liability for consequences of modifications over which it has no control:

1. The product must be operated only in its original condition as delivered.
2. Use only original spare parts from Schmalz.
3. The product must be operated only in perfect condition.

3 Product Design



- | | |
|---|--|
| 1 | Finger module insert (FING-MONT) |
| 2 | Sealing screw (VRS-HEX)
Tension rod (TIE-ROD) |
| 3 | Spacer (SPACER) |
| 4 | Distributor (HUB-MOD) |

- | | |
|---|---------------------------|
| 5 | Sealing screw (VRS-CAP) |
| 6 | Robot adapter (ROB-AD) |
| 7 | Pneumatic connection |
| 8 | Finger modules (FING-MOD) |

4 Configurations

Parallel EOAT (End Of Arm Tool)

Gripping distance [mm]	Compact finger modules		Mini finger modules	
	Spacer size [mm]	Tension rod length [mm]	Spacer size [mm]	Tension rod length [mm]
N/A	Blind plug	35	Blind plug	35
20	None	75	—	—
30	5	85	—	—
40	10	95	None	85
50	15	105	5	95
60	20	115	10	105
70	25	125	15	115
80	30	135	20	125
90	35	145	25	135
100	40	155	30	145
110	—	—	35	155
120	—	—	40	165

5 Technical Parameters

Max. load	≤ 10 kg ¹⁾
Operating pressure	- 0.69 to 0.97 bar
Operating medium	Compressed air, oiled or unoled in accordance with ISO 8573-1:2010 [5:5:4]
Operating temperature	from -20 to 45 °C
Workpiece width	20 to 300 mm (more through special configurations)
Workpiece temperature	from -40 to 100° C
Protection class	IP69K
Materials	Finger: Silicone Gripper with food-safe design: POM, stainless-steel, silicone Gripper with industrial design: POM, aluminum, silicone

¹⁾ Depending on the application

6 Transportation and Storage

6.1 Checking the Delivery

1. Compare the entire delivery with the supplied delivery notes to make sure nothing is missing.
2. Damage caused by defective packaging or occurring in transit must be reported immediately to the carrier and J. Schmalz GmbH.

6.2 Storage



NOTE

The effects of ozone, light (especially UV), heat, oxygen, humidity as well as mechanical influences can reduce the service life of rubber products.

Damage to the finger gripper due to incorrect storage!

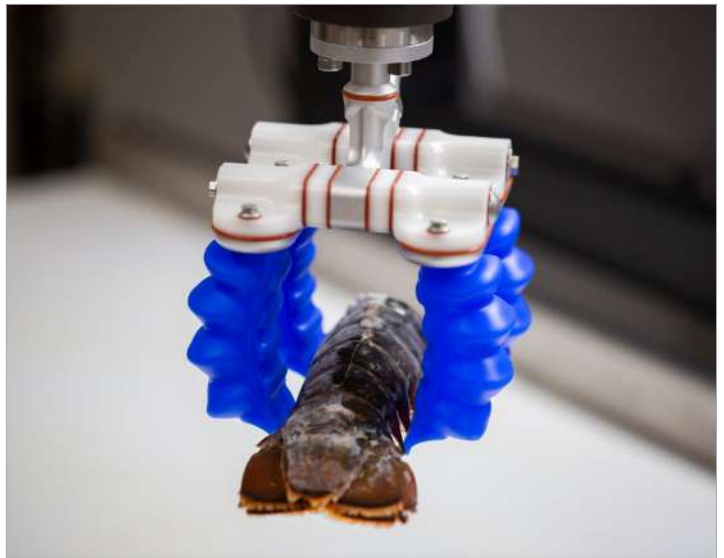
- ▶ Store the finger gripper in a cool place (0° C to +15°C, max. 25° C) that is dark, dry, low in dust and offers protection from the weather, ozone and drafts. It should also be free of tension (e.g. stacked appropriately to avoid deformation).

- ▶ Close all openings with adhesive tape.

7 Description of the Function

The finger gripper operates using the air pressure inside the gripping fingers.

In order for the gripping fingers to move, one side of the material is designed in such a way that it is less stretchy or does not stretch at all. When the pressure inside increases, the finger therefore bends around this side. When the pressure is released, the finger retracts. The gripping fingers are made from soft, stretchy plastic to ensure optimum gripping force.



8 Installation

8.1 Installation Instructions



⚠ CAUTION

Compressed air or vacuum in direct contact with the eye

Severe eye injury!

- ▶ Wear eye protection.
- ▶ Do not look into compressed air openings.
- ▶ Do not look into vacuum openings, e.g. suction cups.



⚠ CAUTION

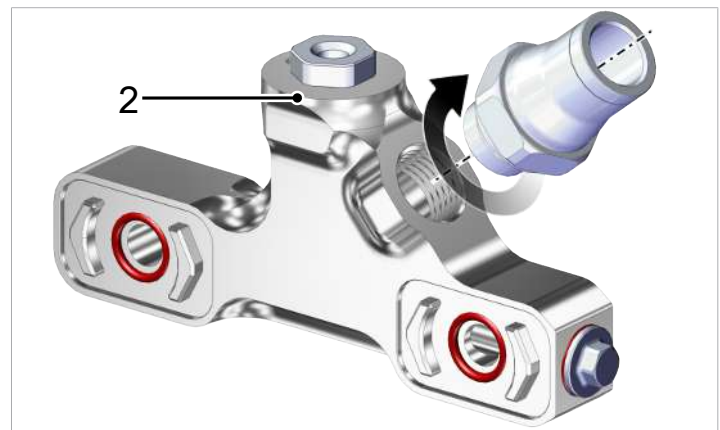
Noise pollution caused by exhaust air or leakage during operation

Hearing damage!

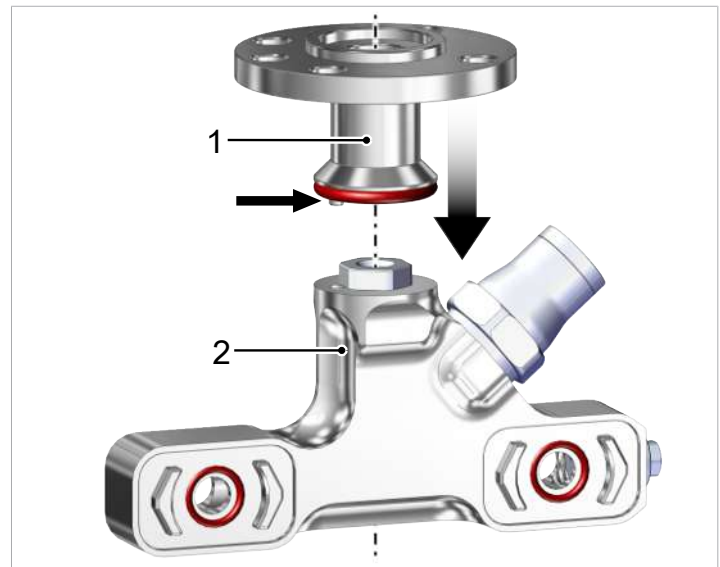
- ▶ In the event of leakage, check connections and lines and remedy leakages.
- ▶ Wear ear protection.

8.2 Mounting

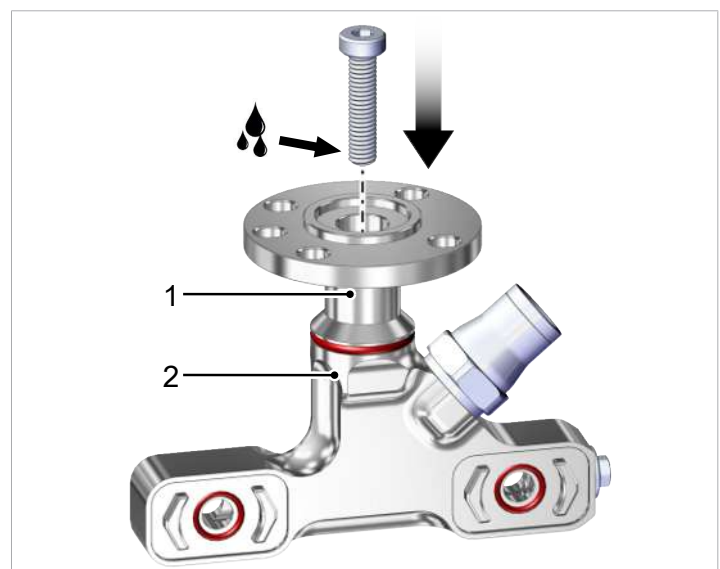
1. Mount the plug-in screw union on the distributor (2) and tighten to 6 Nm.



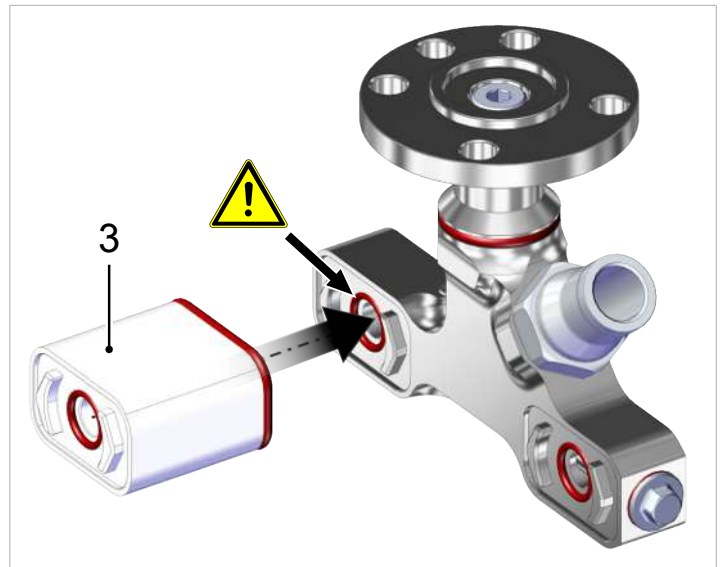
2. Insert the robot adapter (1) including the O-rings in the correct position (note the cam position) in the distributor (2). Make sure the contact surfaces are clean and dry.



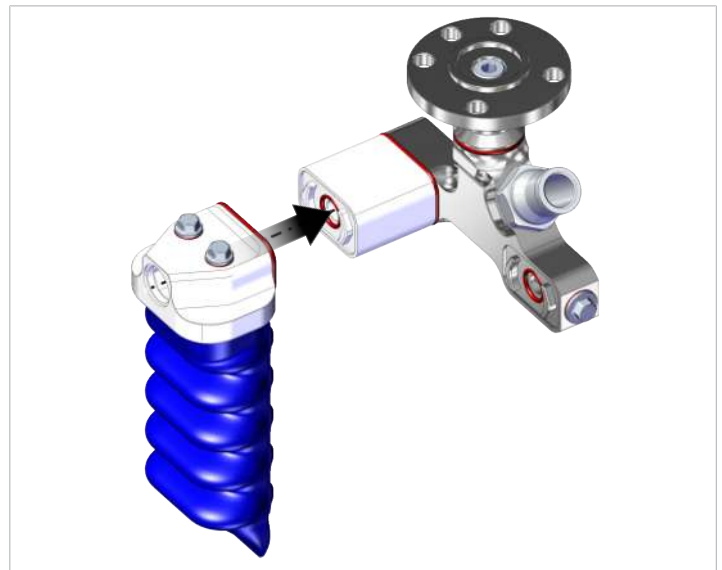
3. Secure the robot adapter (1) to the distributor (2) with the hub bolt. Tighten the hub bolt to 7.4 Nm. We recommend applying anti-seize gel to the M6 bolt before installation.



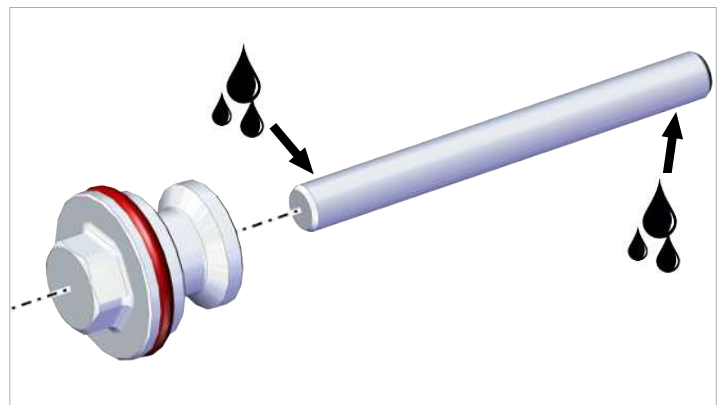
4. Mount the selected spacers (3) in the correct position on the distributor (if required) and press them firmly into place.
Make sure the O-rings are installed on the distributor and have not come loose during shipping.



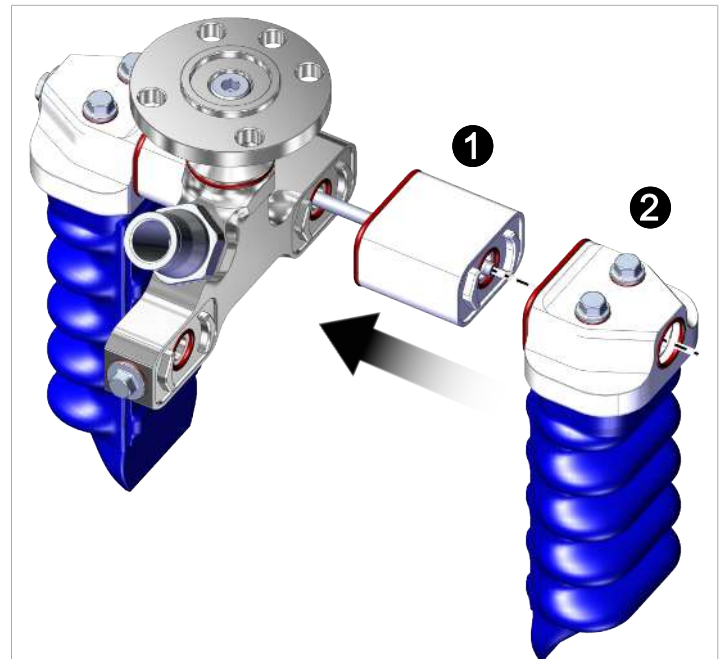
5. Mount the finger module on the spacer.
Note: If no spacers are used, the finger modules can be mounted directly on the distributor.



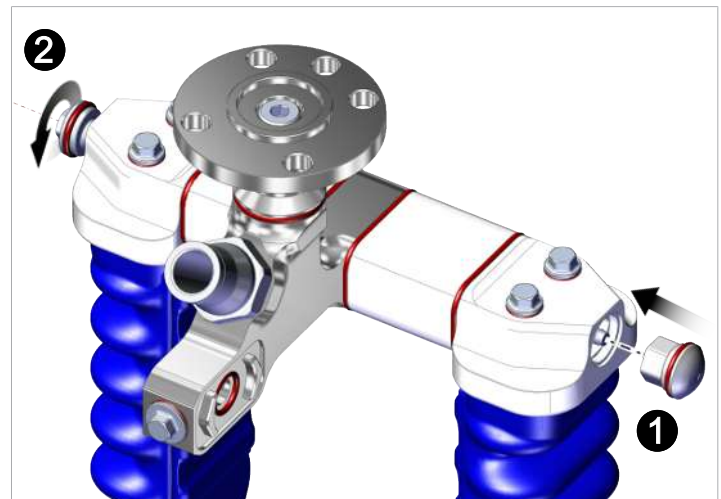
6. Apply anti-seize gel to both ends of the selected tension rod, and tighten the size M4 hexagonal nut on the tension rod.
Note: Use the spacer and tension rod table Configurations to determine which tension rod is best for your gripper.



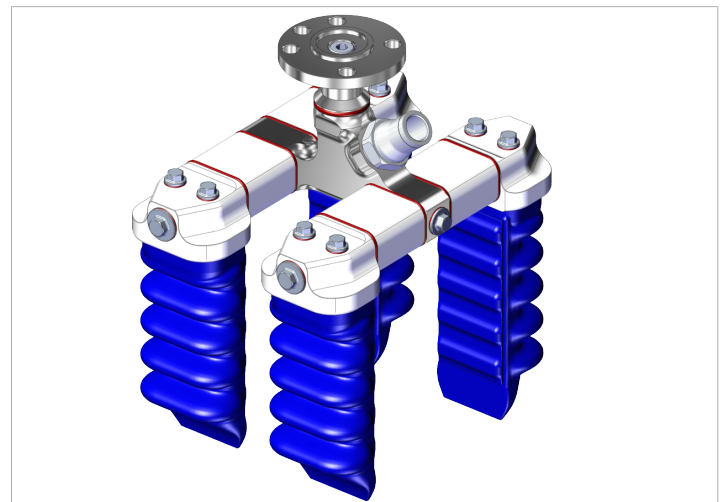
7. Thread the tension rod through the installed finger module and spacer (if installed). If necessary, install the second spacer in the correct position on the opposite side of the distributor; press the spacer firmly against the distributor **1** and position the finger module and press firmly **2**.



8. **Note:** Before mounting the tension rod, make sure that all O-rings and seals are in place and positioned correctly. Slide the M4 sealing cap nut at the end of the tension rod into the recess on the finger base of the finger module **1**. To secure the spacers and finger modules, tighten the hexagonal nut on the tension rod to 2.2 Nm **2**.



9. Repeat steps 4 through 8 to attach other spacers and finger modules to the distributor.



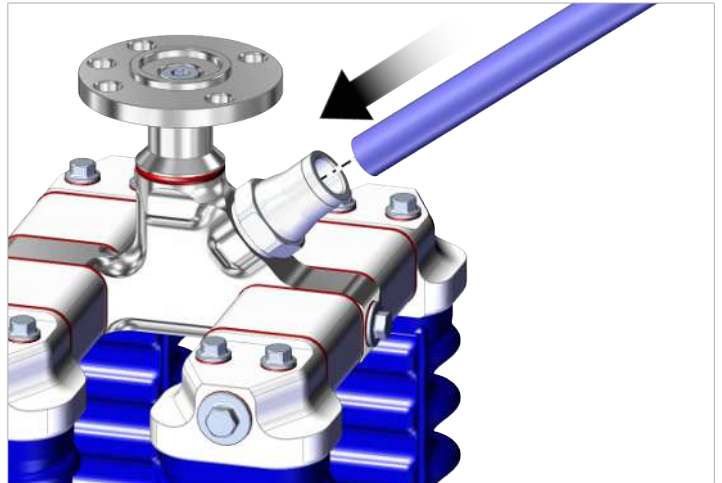
10. After the gripper has been in its operating environment for at least 8 hours, tighten the center hub bolt with a torque of 7.4 Nm.

8.3 Pneumatic connection

The vacuum hose is mounted on the pneumatic connection.

- ✓ The appropriate hose is ready for use.

1. Push the hose into plug-in screw union as far as possible.



2. Manually check the hose for tightness in the plug-in screw union by pulling on the hose.

9 Cleaning the Product



NOTE

Incorrectly cleaning the product and its components

Damage to the product or individual components due to aggressive cleaning agents or excessive temperatures!

- ▶ For cleaning, use only cleaning agents that do not corrode or damage the materials used.
- ▶ Do not use sharp-edged objects (wire brushes, sandpaper, etc.).
- ▶ Do not exceed the specified max. temperature during cleaning.

To safely clean the product, its materials must not react with the cleaning agent and antimicrobial chemicals (disinfectants).

When cleaning the parts, a maximum temperature of 80° C must be observed.

- i** Moisture inside the product may cause malfunctions.
Do **not** clean the inside of the product. The inside of the product must be dry before operation.

- i** The type and frequency of cleaning is the responsibility of the operating company.

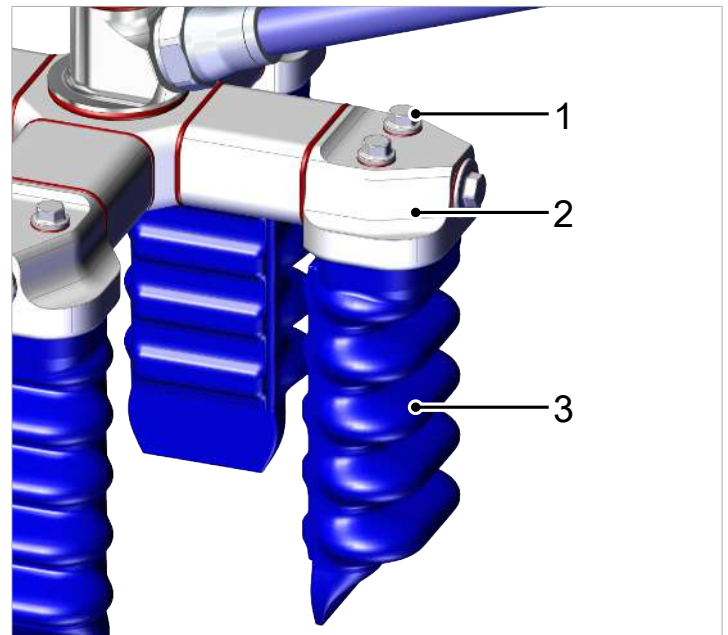
10 Replacing the Finger Module Insert

Overview

The section below explains the work steps for replacing worn or damaged finger module inserts in all Schmalz mGrip™ EOATs with compact finger modules.

Tools required:

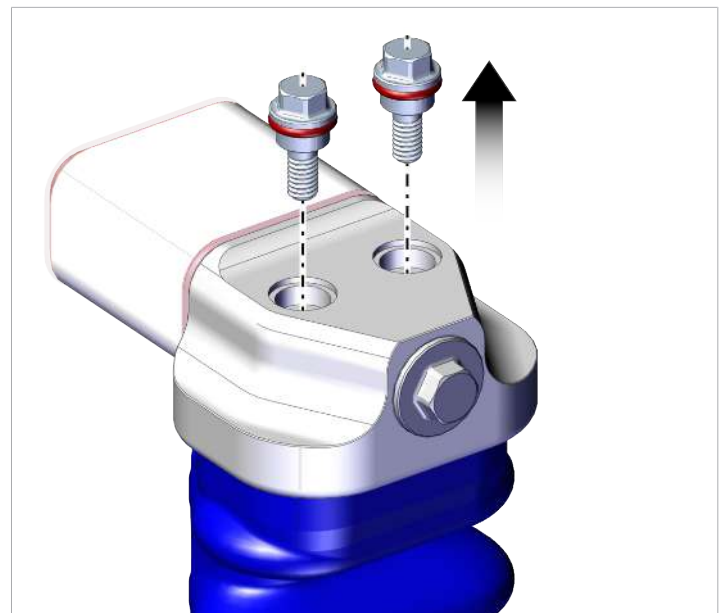
- Torque wrench with 6 mm nut driver bit, suitable for 1.5 Nm
- Food-grade anti-seize thread lubricant



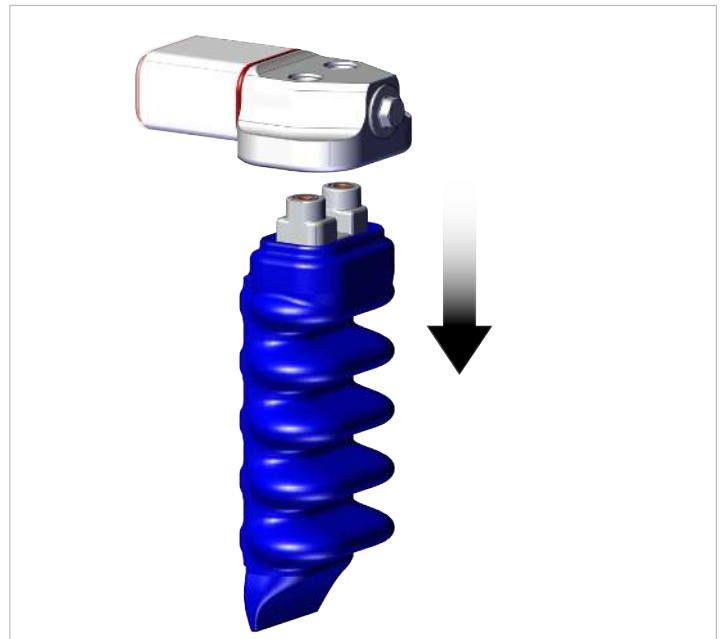
1	Sealing screw	3	Finger module insert (FING-MONT)
2	Finger base (FING-COMP BASE)		

- ✓ You **do not** have to remove the finger base (2) to replace the finger module insert.
- ✓ The corresponding number of replacement finger module inserts (FING-MOUNT) are available.

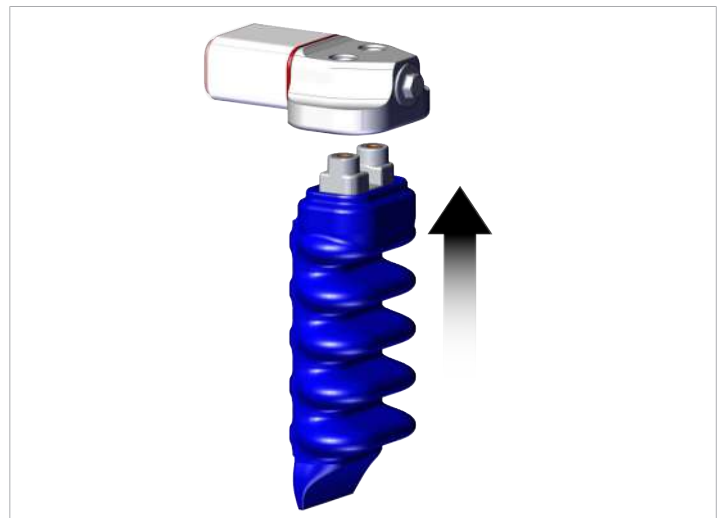
1. Using a 6 mm socket, remove the two M4 seal screws and set them aside for later installation.



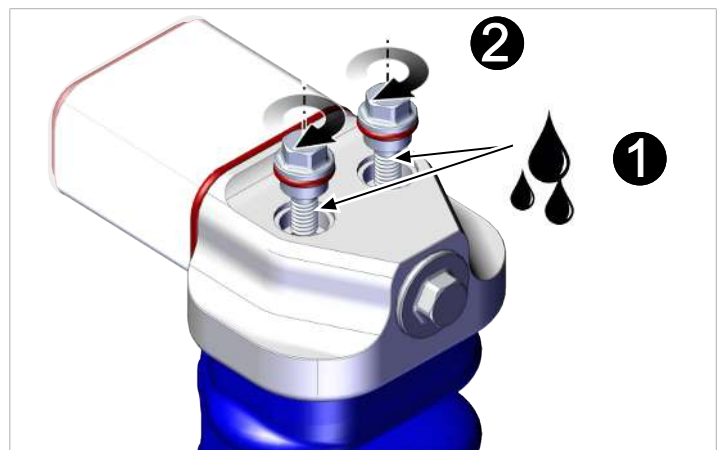
2. Carefully pull the finger module insert away from the finger base.



3. Mount the new finger module insert **in the correct position** on the finger base (FING-COMP BASE).



4. Before mounting, apply food-grade anti-seize thread lubricant to the two M4 sealing screws **1** and then install them. Tighten the screws with a tightening torque of 1.5 Nm. **2**.



11 Disposing of the Product

Recover the disassembled parts for recycling or reuse (provided no agreement on return or disposal has been made).

1. Dispose of the product properly after replacement or decommissioning.
2. Observe the country-specific guidelines and legal obligations for waste prevention and disposal.