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**Published by**

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## Table of contents

1	Function block “FB_ECBPMi” .....	4
1.1	Brief description .....	4
1.2	Image of function block.....	4
1.3	Parameter - Input.....	5
1.4	Parameter - Output.....	6
2	Appendix .....	7
2.1	List of abbreviations .....	7
2.2	Note.....	7

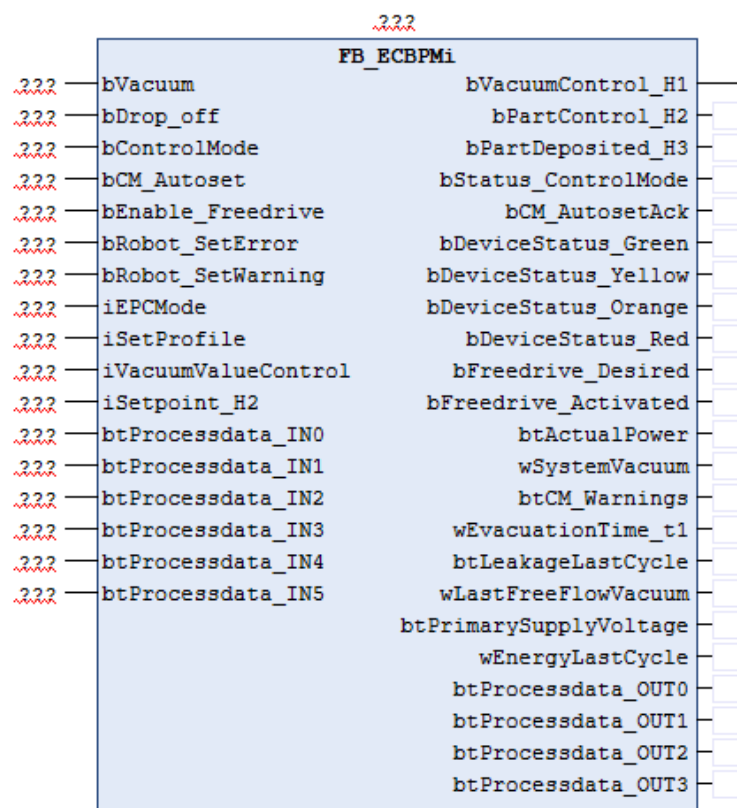
# 1 Function block "FB\_ECBPMi"

## 1.1 Brief description

This function block controls the Processdata of Schmalz ECBPMi with IO-Link.

## 1.2 Image of function block

Example of function block:



### 1.3 Parameter - Input

name	data type	description
bVacuum	BOOL	Request for suction
bDrop_off	BOOL	Request to drop-off
bControlMode	BOOL	Control Mode (see: iVacuumValueControl)
bCM_Autoset	BOOL	Automatic determination and storage in the active profile of max. leakage rate (-L-) and evacuation time (t-1) of last cycle
bEnable_Freedrive	BOOL	Enable "manual control" mode via the higher-level control unit
bRobot_SetError	BOOL	Error is set by higher-level control unit and transferred to error status
bRobot_SetWarning	BOOL	Warning is set by higher-level control unit and transferred to warning status
iEPCMode	INT	Request for EPC data can be controlled as following: 0 = no request 1 = request for values of EPC-Select 0 2 = request for values of EPC-Select 1 3 = request for values of EPC-Select 2 4 = request for values of EPC-Select 3 5 = values are automatically picked up
iSetProfile	INT	Choice of desired vacuum profile (0 – 3)
iVacuumValueControl	INT	bControlMode = 0 : setting setpoint value bControlMode = 1 : engine speed control
iSetpoint_H2	INT	Setpoint for vacuum limit value H2 [10mbar]
btProcessdata_IN0	BYTE	Input byte 0 of process data
btProcessdata_IN1	BYTE	Input byte 1 of process data
btProcessdata_IN2	BYTE	Input byte 2 of process data
btProcessdata_IN3	BYTE	Input byte 3 of process data
btProcessdata_IN4	BYTE	Input byte 4 of process data
btProcessdata_IN5	BYTE	Input byte 5 of process data

## 1.4 Parameter - Output

name	data type	description
bVacuumControl_H1	BOOL	Vacuum value within setpoint area (only in setpoint mode)
bPartControl_H2	BOOL	Switch-on value signal output „Part control“
bPartDeposited_H3	BOOL	Part deposited
bStatus_ControlMode	BOOL	Status of control function
bCM_AutoSetAck	BOOL	Active when CM Autostart completes successfully
bDeviceStatus_Green	BOOL	Device is working optimally
bDeviceStatus_Yellow	BOOL	Device is working but there are warnings
bDeviceStatus_Orange	BOOL	Device is working but there are severe warnings
bDeviceStatus_Red	BOOL	Device is not working properly
bFreemove_Desired	BOOL	Request "manual control" mode to the higher-level control unit
bFreemove_Activated	BOOL	Activates "manual control" mode to the higher-level control unit
btActualPower	BYTE	Actual Power (%)
wSystemVacuum	WORD	System vacuum (mBar)
btCM_Warnings	BYTE	CM Warnings
wEvacuationTime_t1	WORD	Evacuation time t1 (ms)
btLeakageLastCycle	BYTE	Leakage of last handling cycle (mbar/s)
wLastFreeFlowVacuum	WORD	Last free flow vacuum (mbar)
btPrimarySupplyVoltage	BYTE	Input voltage (V)
wEnergyLastCycle	WORD	Energy consumption of last handling cycle (Ws)
btProcessdata_OUT0	BYTE	Output byte 0 of process data
btProcessdata_OUT1	BYTE	Output byte 1 of process data
btProcessdata_OUT2	BYTE	Output byte 2 of process data
btProcessdata_OUT3	BYTE	Output byte 3 of process data

## 2 Appendix

### 2.1 List of abbreviations

abbreviation	description
FB	Function block
EPC	Energy- and Processcontrol
CM	Condition Monitoring
EM	Energy Monitoring
PM	Predictive Maintenance

### 2.2 Note

- The byte order of the product is represented as big endian.
- The triggering of the vacuum must be carried out in accordance with the corresponding ejector variant (e.g., NO, NC, IMP).

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Version 01 | 06.2021